## Scorpion SII-2205-1585 Motor Propeller Data

| Motor Wind 34-Turn Delta |  | Motor Kv 1585 RPM/Volt |  | No-Load Current lo = 0.47 Amps @ 10v |  | Motor Resistance Rm = 0.182 Ohms |  | $\begin{array}{\|c\|} \hline 1 \text { Max } \\ 10 \mathrm{Amps} \\ \hline \end{array}$ | $\begin{gathered} \hline \text { P Max (3S) } \\ 110 \mathrm{~W} \\ \hline \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Outside Diameter $27.9 \mathrm{~mm}, 1.098 \mathrm{in}$. |  | Body Length$23.0 \mathrm{~mm}, 0.906 \mathrm{in}$. |  | Total Shaft Length $42.0 \mathrm{~mm}, 1.654 \mathrm{in}$. |  | Shaft Diameter$2.98 \mathrm{~mm}, 0.117 \mathrm{in}$. |  | $\begin{gathered} \text { Motor Weight } \\ 35.4 \mathrm{gm}, \quad 1.25 \mathrm{oz} \\ \hline \end{gathered}$ |  |
| Prop Manf. | $\begin{aligned} & \hline \text { Prop } \\ & \text { Size } \\ & \hline \end{aligned}$ | Input Voltage | Motor Amps | Watts Input | $\begin{aligned} & \hline \text { Prop } \\ & \text { RPM } \\ & \hline \end{aligned}$ | Pitch Speed | Thrust Grams | Thrust Ounces | Thrust Eff. Grams/W |
| APC | 5.5x4.5-E | 7.4 | 4.32 | 32.0 | 10,256 | 43.7 | 159 | 5.61 | 4.97 |
| APC | $6 \times 4$-E | 7.4 | 4.73 | 35.0 | 9,995 | 37.9 | 200.4 | 7.07 | 5.73 |
| APC | 6x5.5-E | 7.4 | 6.03 | 44.7 | 9,190 | 47.9 | 186.4 | 6.57 | 4.17 |
| APC | $7 \times 4$-E | 7.4 | 6.53 | 48.3 | 8,879 | 33.6 | 307.6 | 10.85 | 6.37 |
| APC | 7x4-SF | 7.4 | 6.41 | 47.4 | 8,915 | 33.8 | 293.2 | 10.34 | 6.18 |
| APC | 7x5-E | 7.4 | 7.72 | 57.1 | 8,142 | 38.6 | 294.7 | 10.40 | 5.16 |
| APC | 7x5-SF | 7.4 | 7.48 | 55.4 | 8,244 | 39.0 | 301.3 | 10.63 | 5.44 |
| APC | 7x6-E | 7.4 | 8.05 | 59.6 | 7,934 | 45.1 | 309.6 | 10.92 | 5.19 |
| APC | 7x6-SF | 7.4 | 8.39 | 62.1 | 7,677 | 43.6 | 278.6 | 9.83 | 4.49 |
| APC | 8x3.8-SF | 7.4 | 8.79 | 65.0 | 7,395 | 26.6 | 381.2 | 13.45 | 5.86 |
| APC | $8 \times 4$-E | 7.4 | 8.31 | 61.5 | 7,765 | 29.4 | 367.9 | 12.98 | 5.98 |
| APC | 8x6-E | 7.4 | 10.11 | 74.8 | 6,557 | 37.3 | 332.7 | 11.74 | 4.45 |
| APC | 8x6-SF | 7.4 | 11.09 | 82.0 | 5,908 | 33.6 | 342.6 | 12.08 | 4.18 |
| APC | 9x3.8-SF | 7.4 | 10.26 | 75.9 | 6,493 | 23.4 | 424 | 14.96 | 5.58 |
| GEM | 8x4.5-C | 7.4 | 9.93 | 73.5 | 6,623 | 28.2 | 385.9 | 13.61 | 5.25 |
| GEM | 9x4.7-C | 7.4 | 10.36 | 76.7 | 6,320 | 28.1 | 419 | 14.78 | 5.47 |
| GWS | $6 \times 3 \times 3$-DD | 7.4 | 3.89 | 28.8 | 10,551 | 30.0 | 202.7 | 7.15 | 7.03 |
| GWS | 7x3.5-DD | 7.4 | 4.54 | 33.6 | 10,108 | 33.5 | 248.6 | 8.77 | 7.39 |
| GWS | 7x3.5x3-DD | 7.4 | 5.39 | 39.9 | 9,564 | 31.7 | 268.4 | 9.47 | 6.73 |
| GWS | 8x4-DD | 7.4 | 7.19 | 53.2 | 8,426 | 31.9 | 362.3 | 12.78 | 6.81 |
| GWS | $8 \times 4 \times 3$-DD | 7.4 | 8.11 | 60.0 | 7,823 | 29.6 | 369.9 | 13.05 | 6.17 |
| GWS | 8x4.5-SF | 7.4 | 9.93 | 73.5 | 6,623 | 28.2 | 385.9 | 13.61 | 5.25 |
| GWS | $8 \times 6-\mathrm{HD}$ | 7.4 | 9.63 | 71.3 | 6,869 | 39.0 | 338.1 | 11.93 | 4.74 |
| GWS | 8x6-SF | 7.4 | 10.14 | 75.0 | 6,496 | 36.9 | 368.5 | 13.00 | 4.91 |
| GWS | 9x4.7-SF | 7.4 | 10.36 | 76.7 | 6,320 | 28.1 | 419 | 14.78 | 5.47 |
| GWS | 9x5-DD | 7.4 | 9.81 | 72.6 | 6,763 | 32.0 | 428.8 | 15.13 | 5.91 |
| GWS | $9 \times 5 \times 3$-DD | 7.4 | 10.87 | 80.4 | 6,001 | 28.4 | 414.2 | 14.61 | 5.15 |
| MAS | $7 \times 4 \times 3$ | 7.4 | 7.50 | 55.5 | 8,275 | 31.3 | 245.4 | 8.66 | 4.42 |
| MAS | $8 \times 6 \times 3$ | 7.4 | 10.67 | 79.0 | 6,241 | 35.5 | 302.4 | 10.67 | 3.83 |
| Prop <br> Manf. | $\begin{aligned} & \hline \text { Prop } \\ & \text { Size } \end{aligned}$ | Input Voltage | Motor <br> Amps | Watts Input | $\begin{aligned} & \hline \text { Prop } \\ & \text { RPM } \end{aligned}$ | Pitch Speed | Thrust Grams | Thrust <br> Ounces | Thrust Eff. Grams/W |
| APC | 4.5x4.1-E | 11.1 | 4.58 | 50.9 | 15,760 | 61.2 | 199.4 | 7.03 | 3.92 |
| APC | 4.7x4.25-E | 11.1 | 5.39 | 59.8 | 15,147 | 61.0 | 207.5 | 7.32 | 3.47 |
| APC | $4.75 \times 4.75-\mathrm{E}$ | 11.1 | 5.79 | 64.3 | 14,855 | 66.8 | 200.5 | 7.07 | 3.12 |
| APC | $4.75 \times 5.5-\mathrm{E}$ | 11.1 | 6.53 | 72.5 | 14,332 | 74.6 | 183.5 | 6.47 | 2.53 |
| APC | 5x5-E | 11.1 | 6.56 | 72.8 | 14,302 | 67.7 | 203 | 7.16 | 2.79 |
| APC | 5.25x4.75-E | 11.1 | 7.04 | 78.1 | 13,916 | 62.6 | 280.5 | 9.89 | 3.59 |
| APC | 5.5x4.5-E | 11.1 | 7.27 | 80.6 | 13,735 | 58.5 | 288.6 | 10.18 | 3.58 |
| APC | $6 \times 4$-E | 11.1 | 7.83 | 86.9 | 13,344 | 50.5 | 372.6 | 13.14 | 4.29 |
| APC | 6x5.5-E | 11.1 | 9.56 | 106.1 | 12,176 | 63.4 | 329.3 | 11.62 | 3.10 |
| APC | 7×4-E | 11.1 | 10.64 | 118.1 | 11,390 | 43.1 | 526.1 | 18.56 | 4.45 |
| APC | 7x4-SF | 11.1 | 10.70 | 118.8 | 11,348 | 43.0 | 512 | 18.06 | 4.31 |
| GWS | $5 \times 3 \times 3$-DD | 11.1 | 4.88 | 54.1 | 15,537 | 44.1 | 273.5 | 9.65 | 5.05 |
| GWS | 5x4.3-DD | 11.1 | 5.02 | 55.7 | 15,424 | 62.8 | 289 | 10.19 | 5.19 |
| GWS | 6x3-DD | 11.1 | 5.83 | 64.7 | 14,809 | 42.1 | 366.5 | 12.93 | 5.66 |
| GWS | $6 \times 3 \times 3$-DD | 11.1 | 6.51 | 72.2 | 14,330 | 40.7 | 384.3 | 13.56 | 5.32 |
| GWS | 7x3.5-DD | 11.1 | 7.63 | 84.7 | 13,487 | 44.7 | 473.8 | 16.71 | 5.59 |
| GWS | 7x3.5x3-DD | 11.1 | 8.98 | 99.7 | 12,550 | 41.6 | 497.6 | 17.55 | 4.99 |
| GWS | 8x4-DD | 11.1 | 11.53 | 128.0 | 10,654 | 40.4 | 601.9 | 21.23 | 4.70 |
| MAS | 7x4x3 | 11.1 | 11.52 | 127.9 | 10,657 | 40.4 | 449.7 | 15.86 | 3.52 |

## Propeller Chart Color Code Explanation

## PLEASE NOTE:

The data contained in this prop chart is based on actual measurements taken in a controlled test environment. The test voltages used are based on a properly sized Li-Po battery for the current draw of the motor being tested. If you are using a larger than normal capacity battery, or a very high C-Rated battery, your actual voltages will be higher than those shown in this chart, and this will result in higer current draw for each prop used. You should always test your power system with a watt meter whenever a prop is used to ensure that you are not exceeding the recommended rating of the motor being used. The prop recommendations in this chart are based on the motor receiving adequate cooling throughout its operation. If your motor is being used inside a cowl, you must provide adequate cooling to the motor and make sure that the motor is not getting too hot during operation.

