

Scorpion User Guide for Jeti Telemetry

1. Connect ESC to your PC using Vlink II cable and set Communication protocol (1E) to Jeti Exbus.

🔊 Sproto platform				the sectors the	
Platform Tools P	Profile Help Disc	connect			Ş
(Reload COM6				Save Set default
Name Tribu SN	ounus ESC-II 12 160008F9	Saved settings	Main 📻 Heli 🕂 Plane 🚺 Prote	ection 🕂 Configuration 🚛 Firmwares 📋 Logs	
BL FW Reset code	24 61 OK	1A Name	Tribunus ESC-II 12S-130A		
Power on time Run count Motor time Discharge, mA	4:39:37 6 1:28 0	1B Device mode	PID with recalculated value		
Throttle	RPM	1C Bec voltage	(5.1 V ×		
		1D Rotation direction	(cw ~)		
Current 0.0 A	Out Power 6.5 %	1E Communication protocol	Jeti ex bus V		
BAT voltage , V CPU temp , °C MSFT temp , °C	-3243.8 0.0 96.0		vbar Jeti ex bus UnscTelem Futaba Sbus2		

2. Connect your Tribunus ESC to your Jeti RX

- Connection is made with a simple male to male servo extension cable (patch cable)
- Use your Empty port with ExBus function (E1, E2) on your duplex receiver to connect to ESC PC port.



3. Go to Menu -> Model -> Device Explorer -> Rex7 -> Alternative Pin Cong and set pin to ExBus (in our example OutPin7/E2 set to ExBus)



4. Go to Timer/Sensors -> Sensors/Logging Setup. You should see Scorpion ESC telemetry connected. If not press "Auto" button and wait for Telemetry sensors to be added to this list.

Tx Default	21%	Tx Default	21%
Sensors/Lo	ogging Setup	Sensors/Lo	ogging Setup
Sensor	Logging		· · · · · · · · · · · · · · · · · · ·
Receiver Voltage/A	ntenna No 🖲	3 Throttle	% Yes 🛃
		4 Power	% Yes 🖲
i ransmitter status ir	ITO >>	5 BEC Volt	V Yes 🖲
Scorpion ESC		6 Temp	°C Yes 🖲
1 Voltage	V Yes 🖲	7 Bat Cap	mAh 🛛 Yes 🖲
2 Current	A Yes 🖲	8 Motor	RPM Yes 🕒
Auto	(9) 🗶 Ok	Auto	(9) 🗶 Ok

5. To show telemetry data on your main screen, go to Timer/Sensors -> Displayed Telemetry -> and Press "Add"



Select sensor to be added to the screen and press "OK" -> then choose the size of display -> then press "Add"



You can see it on your main screen



6. To Add alarm event for your telemetry sensors, go to Timer/Sensors -> Alarms and press "Add"



Choose sensor you need

			21%				
Select Option							
Voltage [V]							
Current [A]							
Throttle [%]							
Power [%]							
BEC Volt [V]							
Fsc			Ok				
230			Οĸ				
e alarm enabled							
te alarm enabled							
Tx			21%				
e alarm enabled	■ larm		21%				
e alarm enabled Tx Default A Sensor	■ larm	Curre	∎ <u>21%</u> nt [A] ₽				
Tx Default Default Sensor Enabled	■ larm	Curre	<u>21%</u> nt [A] €				
Tx Default Default A Sensor Enabled Condition	■ larm X <	Curre	[21% nt [A] € ✓				
Tx Default Default Sensor Enabled Condition File	∎ larm X <	Currei	■ 21% nt [A] ● ✓ 0.0A ● … ●				
Tx Default Default Sensor Enabled Condition File Activation Switch	∎ larm X <	Currei	■ 21% nt [A] ● ✓ 0.0A ● … ●				
Tx Default Default Sensor Enabled Condition File Activation Switch Repeat	∎ larm X <	Currei	■ 21% nt [A] ● ✓ 0.0A ● … ● … ●				
Tx Default Default Sensor Enabled Condition File Activation Switch Repeat	∎ larm X <	Curre	■ 219 nt [A] ● 0.0A ● ● ●				

And set condition for alarm



Press "Ok" and you will see new alarm added.





20%

Priority

Low 🕒

Low 🖲

Low 🖲

Low 🖲

Low 🖲

Ok

7. If you need Telemetry voice assistant, go to the Timer/Sensors ->Voice output -> Sensors & Variables

	efault		20%					
Sensors & Variables								
Sensor	Repeat	Trigger	Priority					
Voltage	eRx 🗙	×	Low 🖲					
Antenna	a1 🗙	×	Low 🖲					
Antenna	a 2 🗙	×	Low 🖲					
Voltage	x	×	Low 🖲					
Current	×	×	Low 🖲					
Throttla	<u> </u>	-						
			Ok					

And setup Repeat and Trigger conditions for each sensor output.